

Debarking mechanism

The invention relates to a debarking mechanism for the excortication or pretreatment of trees for separately performed final barking and for the
5 expulsion of at least some of the removed barks from a wood flow passing through the debarking mechanism, said debarking mechanism comprising a number of rotatable debarking shafts extending parallel to the advancing direction of the trees to be fed therethrough, which are provided with a
10 number of teeth extending beyond the circumferential surface of the shaft and adapted to strip bark off the presently processed trees transversely to the lengthwise direction of the trees and at the same time to convey the trees transversely relative to said shafts, and said shafts, together with the teeth thereof, being adapted to constitute at least a section of a support
15 surface, upon which the presently processed trees travel through the debarking mechanism, and said shafts being adapted to each other in such a way that the processed trees perform a circular motion in the debarking mechanism, in which motion the trees are forced upon the support surface constituted by the debarking shafts, by the action of their rotatory motion, in their turn into the upper position, from which they roll down to the lower
20 position above the other trees being processed in the debarking mechanism.

This type of prior known debarking mechanisms are provided with finger plates between the uppermost debarking shaft and the side wall of the
debarking mechanism - in some mechanisms also between the debarking
25 shafts - to prevent trees from getting wedged between the debarking shaft and the side wall of the debarking mechanism or between two debarking shafts and thus to prevent the wedged tree from getting broken.

The barks can usually get out from between the debarking shaft and the
30 fingerplate or between two debarking shafts. The barks getting off the trees in long strips, instead, cause problems by stuffing the gaps between the

uppermost debarking shaft and the related fingerplates, thus causing the barks to gather into big lumps at these uppermost finger plates.

5 In order to eliminate these disadvantages, the debarking mechanism of the invention has been arranged in such a way, that the uppermost debarking shaft has been provided with a guiding surface, said guiding surface together with the uppermost debarking shaft forming a slot converging in the rotational direction of the debarking shaft. The mentioned guiding surface, on one hand, helps the barks to get into the said slot and, on the other
10 hand, prevents the trees from getting into the slot between the guiding surface and the uppermost debarking shaft.

The guiding surface is preferably provided with grooves in order to arrange said guiding surface and the teeth of the uppermost debarking shaft
15 interlocked.

A freely rotating roller or a roller rotated by a suitable driving apparatus has proved to be the most efficient form of application of the guiding surface.

20 In yet another preferable application of the invention, the higher the debarking shaft lies, the bigger the selected circumferential speed of the debarking shaft is. This arrangement, on one hand, prevents the trees from getting wedged between the debarking shafts and, on the other hand, causes the barks to get out from the debarking mechanism easier.

25 At least one of the debarking shafts, most preferably the uppermost debarking shaft, has been moved sideways towards the inner part of the debarking mechanism in such a way that the said debarking shaft makes the trees conveyed by the lower debarking shaft to change their direction of
30 motion so that when dividing the motion into a horizontal and a vertical

component, the horizontal component of motion points towards the inner part of the debarking mechanism.

5 The new position of the uppermost debarking shaft causes that the trees, at the best, cannot at all go over the uppermost debarking shaft, nor can the trees, as a result of the above, hinder the barks from going into the slot between the uppermost debarking shaft and the said guiding surface.

10 The invention will now be described in more detail with reference to the accompanying drawings, in which:

Fig. 1 shows the debarking shafts of the state-of-the-art debarking mechanism in a schematic side view.

15 Fig. 2 shows a section along a line II-II in fig. 1.

Fig. 3 shows a section picture consistent with fig. 2 of the debarking mechanism in accordance with the first application of the invention.

20 Fig. 4 shows a section consistent with fig. 2 of the debarking mechanism in accordance with the second application of the invention.

Fig. 5 shows a section consistent with fig. 2 of the debarking mechanism in accordance with the third application of the invention.

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Fig. 6 shows a partial picture of the direction of pile VI in fig. 5.

The debarking mechanism 1 shown in the drawings is intended for the excortication or pretreatment of trees 2 for separately performed final
30 barking and for the expulsion of at least some of the removed barks from a wood flow passing through the debarking mechanism.

The debarking mechanism 1 is provided with a number of rotatable debarking shafts 3, 3' extending parallel to the advancing direction A (fig. 1) of the trees 2 to be fed therethrough, said debarking shafts having each end thereof pivoted to the end plates 13 (fig. 1) at the ends of the debarking mechanism 1. To rotate the shafts 3, 3', one end or both ends are provided with for example a sprocket 14. The shafts 3, 3' are rotated in the direction of the pile 5 (fig. 2).

The debarking shafts 3, 3' are provided with a number of teeth 4 extending beyond the circumferential surface of the debarking shaft and adapted to strip bark off the presently processed trees 2 transversely to the longitudinal direction of the trees and at the same time to convey the trees transversely relative to said debarking shafts.

The debarking shafts 3, 3', together with the teeth 4 thereof, constitute a part of a support surface for carrying the trees 2 through the debarking mechanism 1. The figures 1 and 2 show an example of a state-of-the-art mechanism comprising four debarking shafts 3, 3', said shafts being adapted relative to each other to form an inclined plane as best shown in fig. 2. The debarking shafts 3, 3' form a sloping plane also in the advancing direction A of the trees. Other than that, the support surfaces comprise solid surfaces 15, 16 which are designed for providing, together with the support surface constituted by the debarking shafts, an open-ended chute extending from one end the debarking mechanism 1 of to another end.

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The debarking shafts 3, 3' are adapted with each other so that the processed trees 2 perform a circulation motion C in the debarking mechanism, in which motion the trees 2 are positively fed on the support surface formed by the debarking shafts 3,3' effected by the rotatory motion 5 in their turn into the upper position, from which they roll down into the lower position above the other trees 2 in the debarking mechanism 1.

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In the state-of-the-art figures 1 and 2 there is a fingerplate 11 adapted to above the uppermost debarking shaft 3', the purpose of said fingerplate being to prevent the trees from getting wedged between the uppermost debarking shaft 3' and the side wall of the debarking mechanism 1. The barks can usually get out from between the debarking shaft 3' and the fingerplate 11 or between two debarking shafts 3 and fall down onto the bark conveyor below (not shown).

- 10 However, especially the barks getting off in long strips cause sometimes problems by stuffing the slots between the uppermost debarking shaft 3' and the connected fingerplates 11, whereby the barks start gathering into big lumps at the fingerplates 11.
- 15 For the elimination of the said problem, a diagrammatic solution is shown in fig. 3. In this solution at least one debarking shaft, most preferably the uppermost debarking shaft 3', has been moved sideways towards the inner part 6 of the debarking mechanism 1, said debarking shaft forcing the trees 2 conveyed by the lower debarking shafts 3 to change their direction of
- 20 motion so that when dividing the motion into a horizontal and a vertical component, the horizontal component of motion points at the inner part of the debarking mechanism 1. When the selected sideways movement of the debarking shaft 3' is large enough, the trees 2 are prevented from going over the uppermost debarking shaft 3'. Only the barks can go over the uppermost
- 25 debarking shaft 3' and a free passage 7 has been arranged for the barks for their removal from the debarking mechanism 1.

In the example of fig. 3 the said free passage 7 is formed by an opening arranged in the side wall 15 of the debarking mechanism 1 by the debarking shaft 3', through which the barks can freely fall down onto the bark conveyor underneath (not shown).

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In the solution according to fig. 4, a solid guiding surface 8 has been adapted to the uppermost debarking shaft 3', said guiding surface together with the uppermost debarking shaft 3' forming a convergent slot 9 in the direction of rotation 5 of the debarking shaft 3'. In the example of fig. 4 the
5 guiding surface 8 is a plate-like straight surface but it can also have a different kind of form, for example an arched surface. The purpose of the guiding surface 8 is primarily to guide the barks as efficiently as possible out of the debarking mechanism 1 but at the same time to prevent trees 2 going occasionally over the uppermost debarking shaft 3' from getting out of the
10 debarking mechanism 1 or from getting wedged between the uppermost debarking shaft 3' and the side wall 15 of the debarking mechanism 1. The guiding surface 8 has been adapted so that the barks conveyed by the uppermost debarking shaft 3' collide against it in a sharp angle while going towards the slot 9.

15 In the application example of fig. 5, the guiding surface 8 is formed by a toothless freely rotating or independently rotatable roller resembling the debarking shafts 3, 3' as to construction, in which case the teeth 4 of the uppermost debarking shaft force the barks to get out through the slot 9
20 between the uppermost debarking shaft 3' and the roller 8.

The guiding surface 8 - regardless of whether it is a rotating or fixed guiding surface or whether the guiding surface is plate-formed, cylindrical or of another form - is preferably provided with grooves 10 in order to get the
25 said guiding surface and the teeth 4 of the uppermost debarking shaft 3' interlocked and thus to form the slot 9 to the desired size (fig. 6). Due to this arrangement the bark that, forced by the tooth 4, has at some point penetrated through the slot 9, cannot any more easily come back through the slot 9, and the adjacent teeth 4 force even the rest of the bark strip to
30 penetrate through the slot 9. The movable guiding surface 8 constituted by

the rotatable or freely rotating roller makes it still easier for the barks to get into the slot 9 and through it away from the debarking mechanism 1.

- 5 The circumferential speed of the debarking shaft 3, 3' has been preferably chosen the greater the higher the debarking shaft 3, 3' lies. This arrangement, on one hand, prevents the trees 2 from getting wedged between the debarking shafts 3, 3' and on the other hand makes the removal of barks from the debarking mechanism 1 easier.